# $L^{\infty}$ coefficient operators and non-smooth Riemannian metrics

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#### Setup

Let  $\mathcal M$  be a smooth, complete Riemannian manifold with metric g, Levi-Civita connection  $\nabla$ , and volume measure  $d\mu$ .

Write  $\operatorname{div} = -\nabla^*$  in  $L^2$  and let  $S = (I, \nabla)$ .

Consider the following *uniformly elliptic* second order differential operator  $L_A: \mathcal{D}(L_A) \subset L^2(\mathcal{M}) \to L^2(\mathcal{M})$  defined by

$$L_A u = aS^* A S u = -a \operatorname{div}(A_{11} \nabla u) - a \operatorname{div}(A_{10} u) + a A_{01} \nabla u + a A_{00} u.$$

where a and  $A = (A_{ij})$  are  $L^{\infty}$  multiplication operators.

That is, that there exist  $\kappa_1, \kappa_2 > 0$  such that

Re 
$$\langle av, v \rangle \ge \kappa_1 \|v\|^2$$
,  $v \in L^2$   
Re  $\langle ASu, Su \rangle \ge \kappa_2 (\|u\|^2 + \|\nabla u\|^2)$ ,  $u \in H^1$ 

### The problem

The Kato square root problem on manifolds is to determine when the following holds:

$$\begin{cases} & \mathcal{D}(\sqrt{L_A}) = \mathrm{H}^1(\mathcal{M}) \\ & \left\| \sqrt{L_A} u \right\| \simeq \left\| \nabla u \right\| + \left\| u \right\| = \left\| u \right\|_{\mathrm{H}^1}, \ u \in \mathrm{H}^1(\mathcal{M}) \end{cases}$$

### Theorem (B.-Mc [BMc])

Let  $(\mathcal{M}, g)$  be a smooth, complete Riemannian manifold  $|Ric| \leq C$  and  $inj(M) \geq \kappa > 0$ . Suppose there exist  $\kappa_1, \kappa_2 > 0$  such that

$$\operatorname{Re}\langle av, v \rangle \ge \kappa_1 \|v\|^2$$
  
 $\operatorname{Re}\langle ASu, Su \rangle \ge \kappa_2 \|u\|_{H^1}^2$ 

for  $v \in L^2(\mathcal{M})$  and  $u \in H^1(\mathcal{M})$ . Then,  $\mathcal{D}(\sqrt{L_A}) = \mathcal{D}(\nabla) = H^1(\mathcal{M})$  and  $\|\sqrt{L_A}u\| \simeq \|\nabla u\| + \|u\| = \|u\|_{H^1}$  for all  $u \in H^1(\mathcal{M})$ .

### Stability

### Theorem (B.-Mc [BMc])

Let  $(\mathcal{M}, g)$  be a smooth, complete Riemannian manifold with  $|Ric| \leq C$  and  $inj(M) \geq \kappa > 0$ . Suppose that there exist  $\kappa_1, \kappa_2 > 0$  such that

$$\operatorname{Re} \langle av, v \rangle \ge \kappa_1 \|v\|^2$$
$$\operatorname{Re} \langle ASu, Su \rangle \ge \kappa_2 \|u\|_{H^1}^2$$

for  $v \in L^2(\mathcal{M})$  and  $u \in H^1(\mathcal{M})$ . Then for every  $\eta_i < \kappa_i$ , whenever  $\|\tilde{a}\|_{\infty} \leq \eta_1$ ,  $\|\tilde{A}\|_{\infty} \leq \eta_2$ , the estimate

$$\left\| \sqrt{\mathcal{L}_A} \, u - \sqrt{\mathcal{L}_{A+\tilde{A}}} \, u \right\| \lesssim \left( \|\tilde{a}\|_{\infty} + \|\tilde{A}\|_{\infty} \right) \|u\|_{\mathcal{H}^1}$$

holds for all  $u \in H^1(\mathcal{M})$ . The implicit constant depends in particular on A, a and  $\eta_i$ .

### History of the problem

In the 1960's, Kato considered the following abstract evolution equation

$$\frac{du}{dt} + A(t)u = f(t), \quad t \in [0, T].$$

on a Hilbert space  $\mathcal{H}$ .

In 1962, Kato showed in [Kato61] that for  $0 \le \alpha < 1/2$  and A(t) maximal accretive that

$$\mathcal{D}(A(t)^{\alpha}) = \mathcal{D}(A(t)^{*\alpha}) = \mathcal{D}_{\alpha} = \text{const}, \text{ and}$$
$$\|A(t)^{\alpha}u\| \simeq \|A(t)^{*\alpha}u\|, \quad u \in \mathcal{D}_{\alpha}. \tag{$K_{\alpha}$}$$

Counter examples were known for  $\alpha > 1/2$ .

Kato asked two questions:

- (K1) Does  $(K_{\alpha})$  hold for  $\alpha = 1/2$ ?
- (K2) For the case  $\omega = 0$ , we know (K1) is automatically true, but is

$$\left\| \frac{d}{dt} \sqrt{A(t)} u \right\| \lesssim \|u\|$$

for  $u \in \mathcal{W}$ ?

In 1972, McIntosh provided a counter example in [Mc72] demonstrating that (K1) is false in such generality.

In 1982, McIntosh showed that (K2) also did not hold in general in [Mc82].

The Kato square root problem then became the following.

Suppose  $A\in L^\infty$  is a pointwise matrix multiplication operator satisfying the following ellipticity condition:

$$\operatorname{Re} \langle A \nabla u, \nabla u \rangle \ge \kappa \|\nabla u\|^2$$
, for some  $\kappa > 0$ .

Is it then true that

$$\mathcal{D}(\sqrt{\operatorname{div} A \nabla}) = \operatorname{H}^{1}(\mathbb{R}^{n})$$

$$\left\| \sqrt{\operatorname{div} A \nabla} u \right\| \simeq \|\nabla u\|$$
(K1)

This was answered in the positive in 2002 by Pascal Auscher, Steve Hofmann, Michael Lacey, Alan McIntosh and Phillipe Tchamitchian in [AHLMcT].

# Axelsson (Rosén)-Keith-McIntosh framework

In [AKMc], the authors created a *first-order* framework using the language of Dirac type operators to study such problems.

- (H1) Let  $\Gamma$  be a densely-defined, closed, nilpotent operator on a Hilbert space  $\mathscr{H}$  ,
- (H2) Suppose that  $B_1,B_2\in\mathcal{L}(\mathscr{H})$  such that here exist  $\kappa_1,\kappa_2>0$  satisfying

$$\operatorname{Re} \langle B_1 u, u \rangle \ge \kappa_1 \|u\|^2$$
 and  $\operatorname{Re} \langle B_2 v, v \rangle \ge \kappa_2 \|v\|^2$ 

for 
$$u \in \mathcal{R}(\Gamma^*)$$
 and  $v \in \mathcal{R}(\Gamma)$ ,

(H3) The operators  $B_1, B_2$  satisfy  $B_1B_2\mathcal{R}(\Gamma) \subset \mathcal{N}(\Gamma)$  and  $B_2B_1\mathcal{R}(\Gamma^*) \subset \mathcal{N}(\Gamma^*)$ .

Let 
$$\Gamma_B^* = B_1 \Gamma^* B_2$$
,  $\Pi_B = \Gamma + \Gamma_B^*$  and  $\Pi = \Gamma + \Gamma^*$ .

# Quadratic estimates and Kato type problems

#### Proposition

If (H1)-(H3) are satisfied and

$$\int_0^\infty \left\| t \Pi_B (\mathbf{I} + t^2 \Pi_B^2)^{-1} u \right\|^2 \frac{dt}{t} \simeq \|u\|$$

for  $u \in \overline{\mathcal{R}(\Pi_B)}$ , then

- (i)  $\mathcal{D}(\Gamma)\cap\mathcal{D}(\Gamma_B^*)=\mathcal{D}(\Pi_B)=\mathcal{D}(\sqrt{\Pi_B^2})$ , and
- (ii)  $\|\Gamma u\| + \|\Gamma_B u\| \simeq \|\Pi_B u\| \simeq \|\sqrt{\Pi_B^2} u\|$ , for all  $u \in \mathcal{D}(\Pi_B)$ .

Set 
$$\mathscr{H} = L^2(\mathcal{M}) \oplus (L^2(\mathcal{M}) \oplus L^2(T^*\mathcal{M})).$$

Define

$$\Gamma_{\mathrm{g}} = \begin{bmatrix} 0 & 0 \\ S & 0 \end{bmatrix}, \ B_1 = \begin{bmatrix} a & 0 \\ 0 & 0 \end{bmatrix}, \ \mathrm{and} \ B_2 = \begin{bmatrix} 0 & 0 \\ 0 & A \end{bmatrix}.$$

Then,

$$\Gamma_{\mathrm{g}}^* = \begin{bmatrix} 0 & S^* \\ 0 & 0 \end{bmatrix} \text{ and } \Pi_B^2 = \begin{bmatrix} \mathbf{L}_A & 0 \\ 0 & * \end{bmatrix}$$

and

$$\Pi_{B,\mathrm{g}}(u,0)=(0,u,\nabla u)$$
 and  $\sqrt{\Pi_{B,\mathrm{g}}^2}(u,0)=(\sqrt{\mathrm{L}_A}u,0).$ 

Theorem 1 and 2 are a direct consequence of the following.

#### Proposition

Let  $\mathcal M$  be a smooth, complete manifold with smooth metric g. Suppose there exist  $\eta, \kappa > 0$  such that  $|\mathrm{Ric}_g| \le \eta$  and  $\mathrm{inj}(\mathcal M, g) \ge \kappa$ . Furthermore, suppose that there exist  $\kappa_1, \kappa_2$  such that

Re 
$$\langle av, v \rangle \ge \kappa_1 \|v\|^2$$
,  $v \in L^2(\mathcal{M}, g)$   
Re  $\langle ASu, Su \rangle \ge \kappa_2 \|u\|_{H^1}^2$ ,  $u \in H^1(\mathcal{M}, g)$ .

Then,

$$\int_0^\infty ||t\Pi_B(I + t^2\Pi_B^2)^{-1}u||^2 \frac{dt}{t} \simeq ||u||^2$$

for  $u \in \overline{\mathcal{R}(\Pi_B)}$ .

### Rough metrics

We let  $\mathcal{M}$  be a smooth, complete manifold as before but now let g be a  $C^0$  metric. Let  $\mu_g$  denote the volume measure with respect to g.

#### **Definition**

Let  $h \in C^0(\mathcal{T}^{(2,0)}\mathcal{M})$ . Then, define

$$\left\|\mathbf{h}\right\|_{\mathrm{op,g}} = \mathrm{esssup}_{\mu_{\mathbf{g}}(x)-\mathsf{a.e.}} \ \sup_{|u|_{\mathbf{g}}=|v|_{\mathbf{g}}=1} \left|\mathbf{h}_x(u,v)\right|,$$

and

$$\|\mathbf{h}\|_{\text{op,s,g}} = \sup_{x \in \mathcal{M}} \sup_{\|u\|_{g} = \|v\|_{g} = 1} |\mathbf{h}_{x}(u, v)|.$$

We say that two  $C^0$  metrics g and  $\tilde{g}$  are  $\delta\text{-close}$  if  $\|g-\tilde{g}\|_{\mathrm{op},g}<\delta$  for  $\delta>0.$ 

### Translating from one metric to another

Suppose that we now have a smooth metric  $\tilde{\mathbf{g}}$ . Write  $f_u(v) = \tilde{\mathbf{g}}(u,v) - \mathbf{g}(u,v)$ . By Riesz-Representation theorem, we find that there exists B such that

$$\tilde{g}((I+B)u, v) = g(u, v).$$

That is, exactly, we can absorb the lack of regularity of g in terms of a symmetric, bounded operator in  $\tilde{g}$ . The operator  $\|B\| = \|\tilde{g} - g\|_{op,g}$ . The change of measures

$$\theta = \frac{d\mu_{\rm g}}{d\mu_{\tilde{\rm g}}}$$

is given in terms of I + B.

# Stability of function spaces

#### **Proposition**

Let g and  $\tilde{g}$  be two  $C^0$  metrics on  $\mathcal{M}$ . If there exists  $\delta \in [0,1)$  such that  $\|g-\tilde{g}\|_{\mathrm{op},g} < \delta$ , then

(i) the spaces  $L^2(\mathcal{M},g)=L^2(\mathcal{M},\tilde{g})$  with

$$(1-\delta)^{\frac{n}{4}} \left\| \cdot \right\|_{2,g} \leq \left\| \cdot \right\|_{2,\tilde{g}} \leq (1+\delta)^{\frac{n}{4}} \left\| \cdot \right\|_{2,g},$$

(ii) the Sobolev spaces  $H^1(\mathcal{M},\tilde{g})=H^1(\mathcal{M},g)$  with

$$\frac{(1-\delta)^{\frac{n}{4}}}{1+\delta} \left\| \cdot \right\|_{H^1,g} \leq \left\| \cdot \right\|_{H^1,\tilde{g}} \leq \frac{(1+\delta)^{\frac{n}{4}}}{1-\delta} \left\| \cdot \right\|_{H^1,g}.$$

# $\Pi_B$ under a change of metric

The operator  $\Gamma_{\! g}$  does not change under the change of metric. However,

#### Proposition

 $\Gamma_g^* = \Theta \Gamma_{\tilde{g}}^* C$  where  $\Theta$  is a bounded multiplication operator on  $L^2(\mathcal{M})$  and C is a bounded multiplication operator on  $L^2(\mathcal{M}) \oplus L^2(T^*\mathcal{M})$ .

Thus,

$$\Pi_{B,g} = \Gamma_g + B_1 \Gamma_g^* B_2 = \Gamma_{\tilde{g}} + B_1 \Theta \Gamma_{\tilde{g}}^* C B_2.$$

The idea is to reduce the Kato problem for  $\Pi_{B,g}$  to a Kato problem for  $\Pi_{\tilde{B},\tilde{g}}=\Gamma_{\tilde{g}}+\tilde{B}_1\Gamma_{\tilde{g}}^*\tilde{B}_2$  where  $\tilde{B}_1=B_1\Theta$  and  $\tilde{B}_2=CB_2$  but now with a smooth metric  $\tilde{g}$ .

# **Ellipticity**

Let us define ellipticity of  $L_A$  with respect to a metric h by

$$\operatorname{Re} \langle av, v \rangle_{h} \geq \kappa_{1,h} \|v\|_{2,h}^{2}, \ v \in L^{2}(\mathcal{M})$$

$$\operatorname{Re} \langle ASu, Su \rangle_{h} \geq \kappa_{2,h} \|u\|_{H^{1} h}^{2}, \ u \in H^{1}(\mathcal{M}).$$
(E)

# Ellipticity (cont.)

Then the loss in the ellipticity constants by transferring from one operator to another is as follows.

### Proposition

If  $\|g - \tilde{g}\|_{op,g} \le \delta < 1$ , then assuming (E) with respect to g implies (E) with respect to  $\tilde{g}$  with an appropriate change of the coefficients a and A with ellipticity constants

$$\kappa_{1,\tilde{\mathbf{g}}} = \frac{\kappa_{1,\mathbf{g}}}{(1+\delta)^{\frac{n}{2}}} \quad \text{and} \quad \kappa_{2,\tilde{\mathbf{g}}} = \kappa_{2,\mathbf{g}} \frac{(1-\delta)}{(1+\delta)^{\frac{n}{2}}}.$$

### Theorem (Reduction of the rough problem to the smooth)

Let  $\mathcal M$  be a smooth manifold with a  $C^0$  metric g and suppose that the ellipticity condition (E) is satisfied for  $(\mathcal M,g)$ . Suppose further that there exists a smooth, complete metric  $\tilde g$  satisfying:

- (i) there exists  $\eta>0$  such that  $|\mathrm{Ric}_{\tilde{g}}|_{\tilde{g}}\leq \eta$  ,
- (ii) there exists  $\kappa > 0$  such that  $\operatorname{inj}(\mathcal{M}, \tilde{g}) \geq \kappa$ ,
- (iii)  $\|g \tilde{g}\|_{op,g} < 1$ ,

Then, the quadratic estimate

$$\int_0^\infty ||t\Pi_{B,g}(I + t^2\Pi_{B,g}^2)^{-1}u||_g^2 \frac{dt}{t} \simeq ||u||_{2,g}^2$$

holds for all  $u \in \overline{\mathcal{R}(\Pi_{B,g})}$ .

# Compact manifolds

Given a  $C^0$  metric g, we can always find a  $C^\infty$  metric  $\tilde{g}$  that is as close as we would like in the  $\|\cdot\|_{\mathrm{op},s,g}$  norm by pasting together Euclidean metrics via a partition of unity.

Further if we assume that  $\mathcal{M}$  is compact, then automatically  $|\mathrm{Ric}_{\tilde{\mathbf{g}}}| \leq C_{\tilde{\mathbf{g}}}$  and  $\mathrm{inj}(\mathcal{M}, \tilde{\mathbf{g}}) \geq \kappa_{\tilde{\mathbf{g}}} > 0$ .

#### **Theorem**

Let  $\mathcal M$  be a smooth, compact Riemannian manifold and let g be a  $C^0$  metric on  $\mathcal M$ . Then, the quadratic estimate

$$\int_0^\infty ||t\Pi_{B,g}(I + t\Pi_{B,g}^2)^{-1}u||^2 \frac{dt}{t} \simeq ||u||^2$$

is satisfied for all  $u \in \overline{\mathcal{R}(\Pi_{B,g})}$ .

### The noncompact case

- Although we can obtain arbitrarily close smooth metrics via a partition of unity in the noncompact setting, the desired geometric properties are not automatic.
- Intuition is that the smoothing properties of geometric flows could be utilised to find good close smooth metrics.
- The non-uniqueness of existence of solutions to geometric flows are not an issue since we only require *one* good metric near the initial one.
- A good place to start may be the mean curvature flow since such flows have been studied with rough initial data.
- The first task is to understand the backward behaviour of this flow and the relationship it has to  $\|\cdot\|_{\text{op,g}}$ .

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